

# ReJOIN: A Prototype Query Optimizer using Deep Reinforcement Learning

Ryan Marcus\*, Brandeis University  
Olga Papaemmanouil, Brandeis University

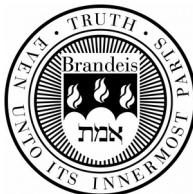
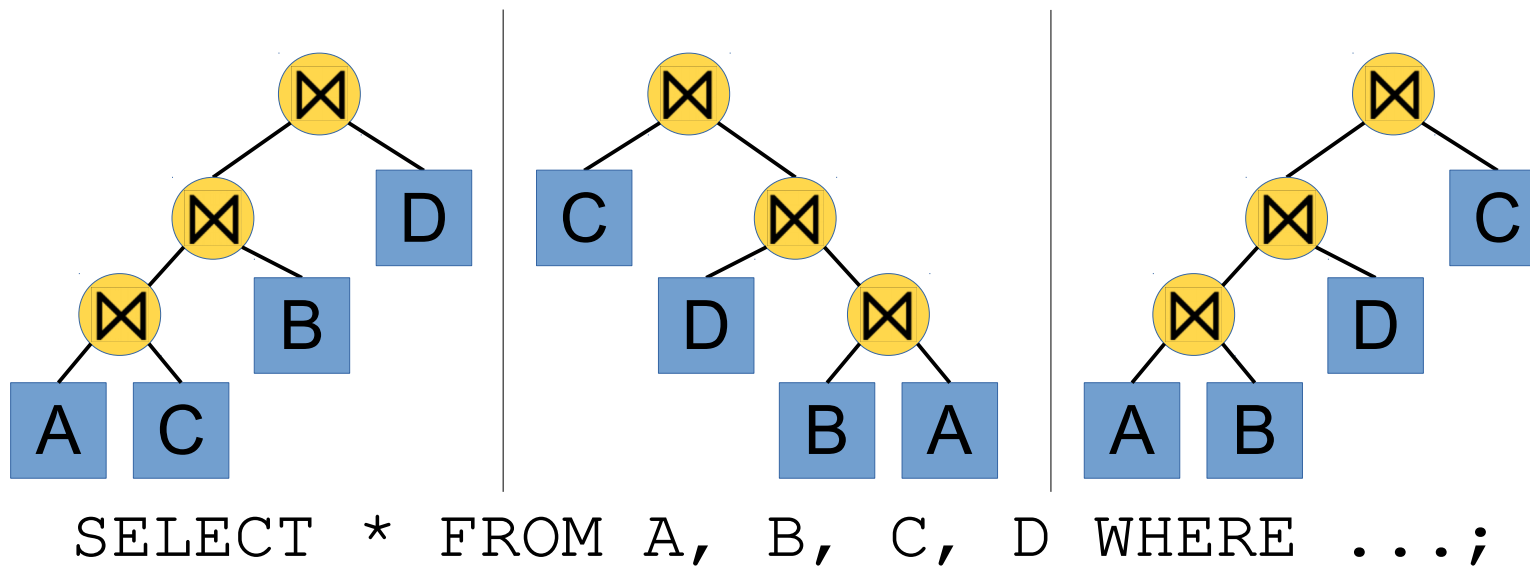
10/3/2018

These slides:  
<http://rm.cab/ibm18>



# Join Order Enumeration

- Classic problem in query optimization
- For 12 joins, ~100 trillion possibilities
- Cost-based optimization (using cost model)



# Join Order Enumeration

- System R: algorithm for best left-deep
- PostgreSQL: bottom-up pairwise, pruned
  - Use a genetic optimizer for  $n > 12$  relations
- SQL Server: complex heuristics
- Other heuristics...
  
- Requires per-DB tuning to get right
- Fire and forget



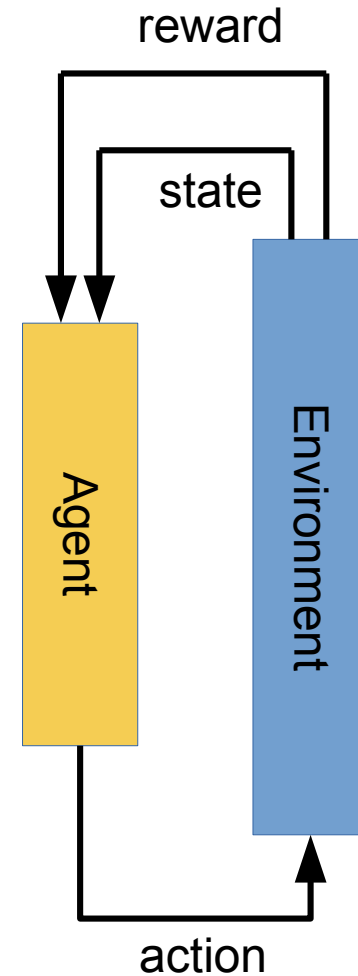
# ReJOIN

- A join order enumerator
- Uses *reinforcement learning*
  - Learns from its mistakes
- Automatically tunes itself over time
- Finds *better* join orderings
- Finds join orderings *faster*
- Even a **straight-forward** application of deep learning produces **interesting results**



# Reinforcement Learning

- Agent observes a *state*
  - Info about the world
  - Set of possible actions
- Agent selects an action, gets:
  - A reward
  - New state
- Goal: maximize reward over time
  - explore and exploit



# Deep Reinforcement Learning

- Previous RL has been severely limited...
  - Q-learning, state table
  - REINFORCE, action space
- Applications of RL to QO have also been limited
  - LEO, self-tuning histograms (cardinality est)
- Deep RL → sudden ability to handle large problems
  - Complex video games, walking, real-world navigation



# ReJOIN

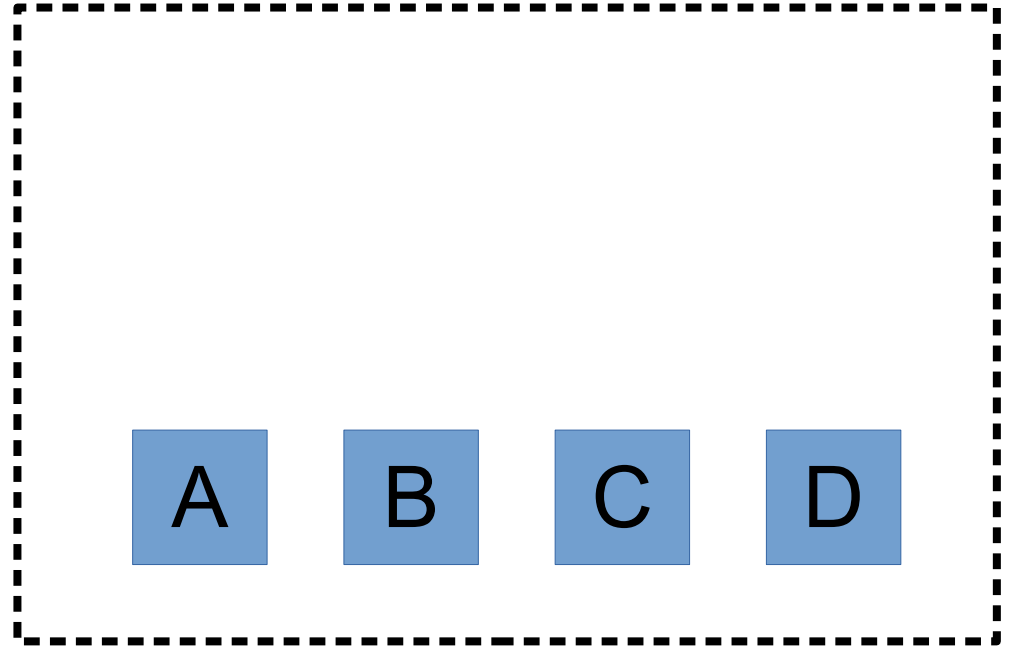
- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost



# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State

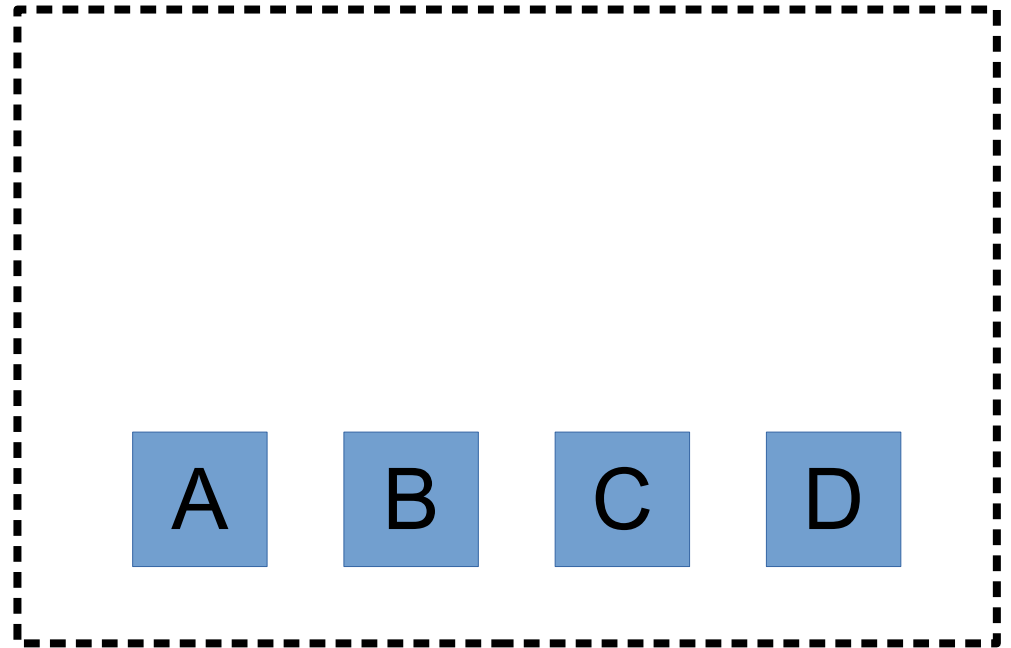




# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State



**Possible actions:**

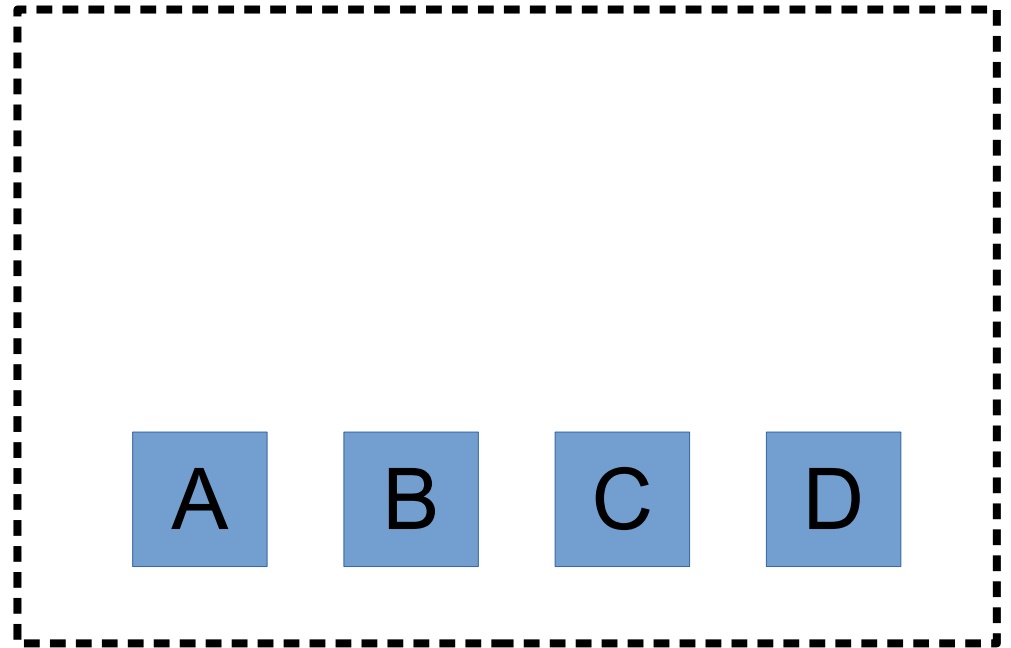
(A, B), (B, A), (A, C), (C, A), (A, D),  
(D, A), (B, C), (C, B), (B, D), (D, B),  
(C, D), (D, C)



# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State



**Possible actions:**

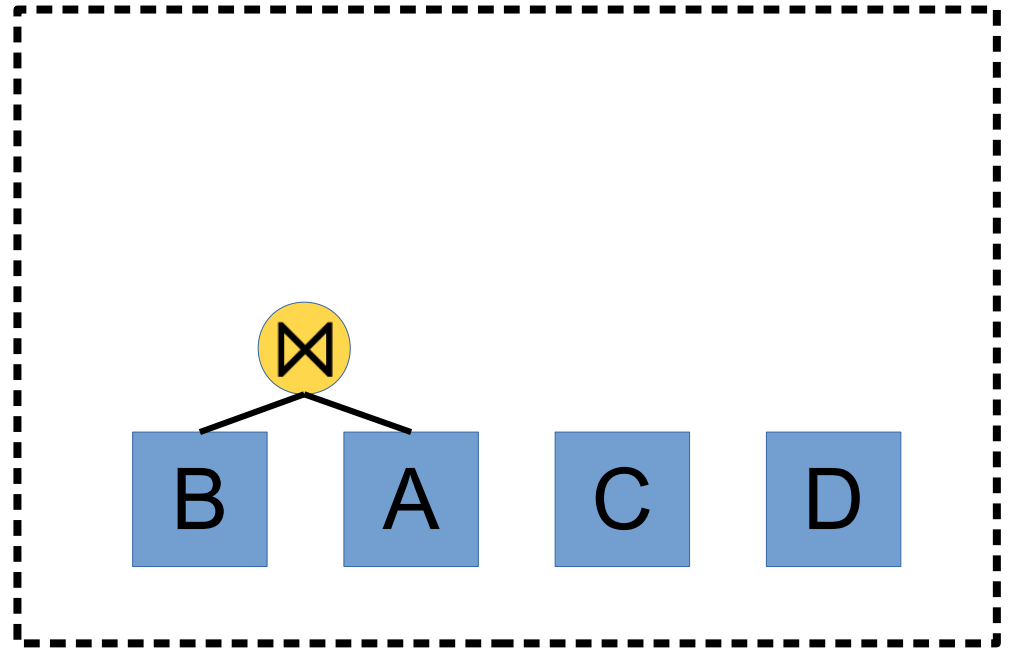
(A, B), (**B, A**), (A, C), (C, A), (A, D),  
(D, A), (B, C), (C, B), (B, D), (D, B),  
(C, D), (D, C)



# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State



**Possible actions:**

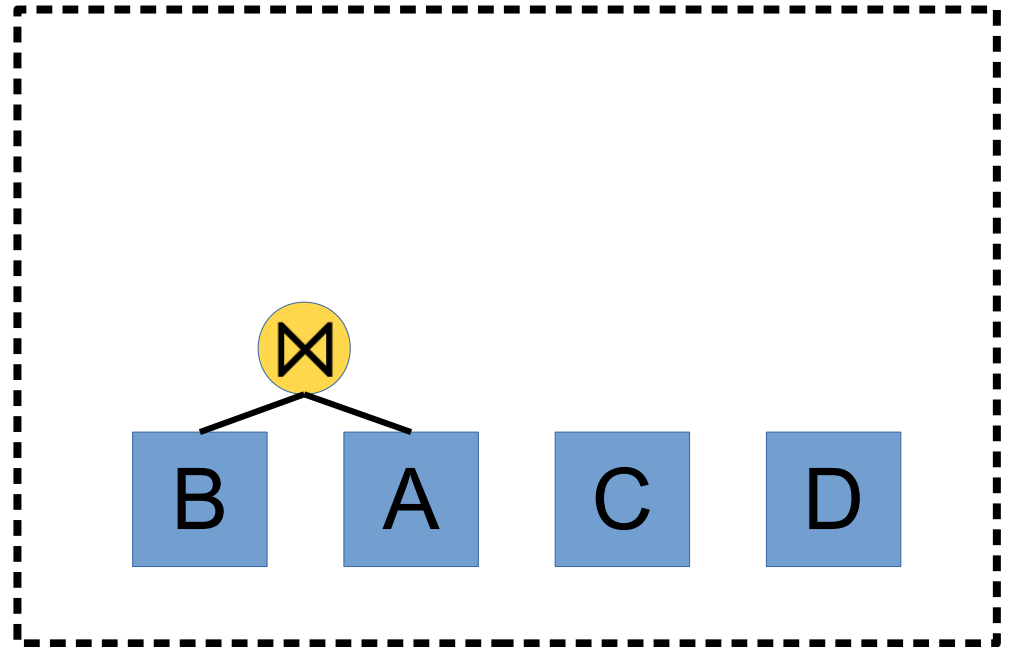
([BA], C), (C, [BA]), ([BA], D),  
(D, [BA]), (C, D), (D, C)



# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State



**Possible actions:**

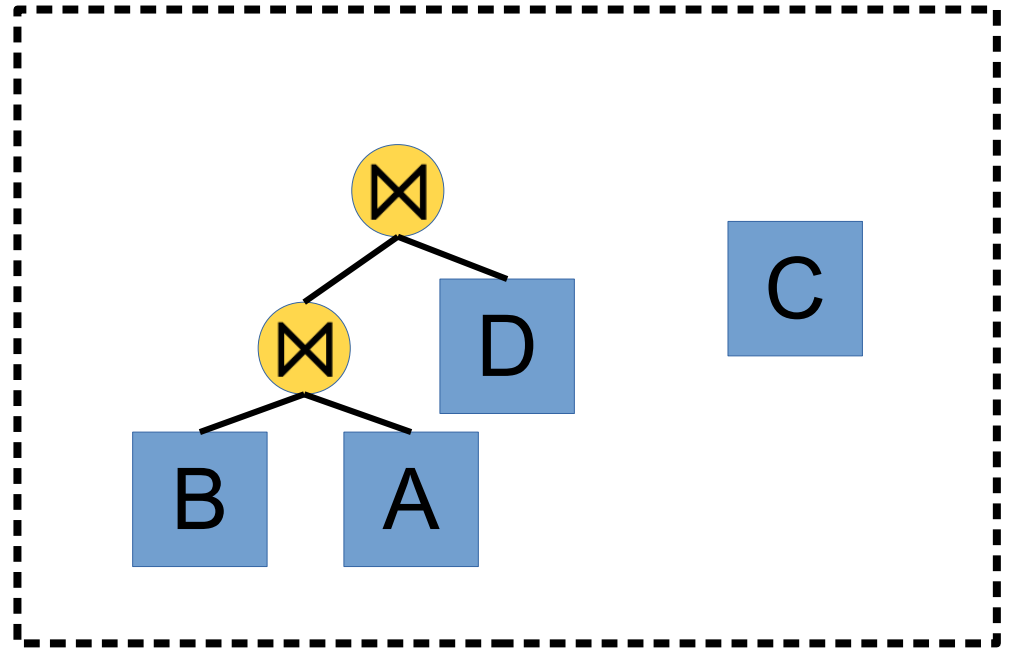
([BA], C), (C, [BA]), ([BA], D),  
(D, [BA]), (C, D), (D, C)



# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State



**Possible actions:**

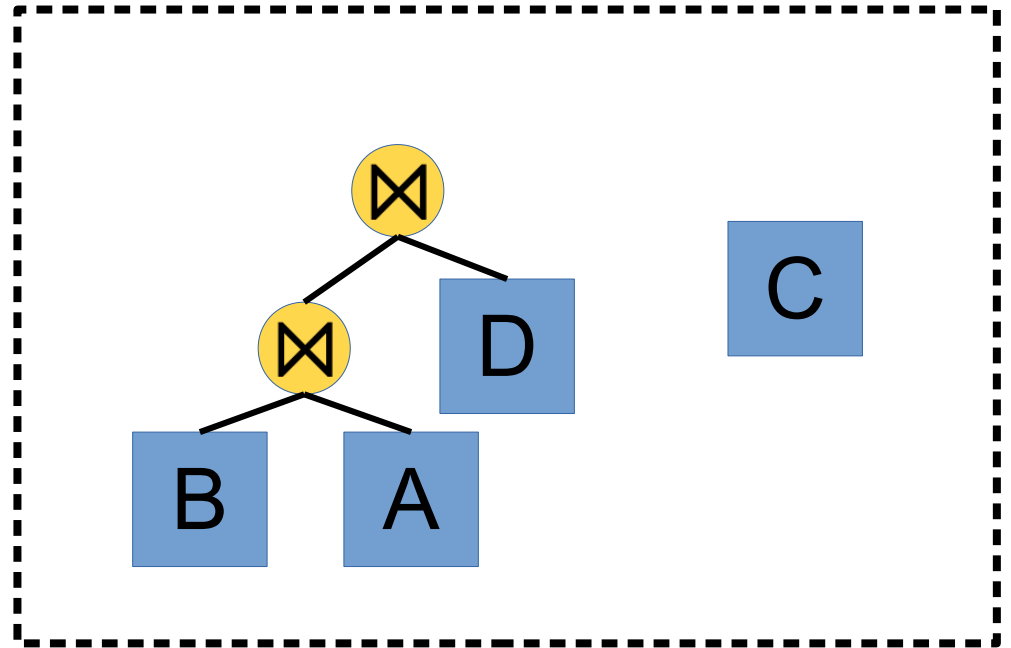
$([[BA]D], C), (C, [[BA]D])$



# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State



**Possible actions:**

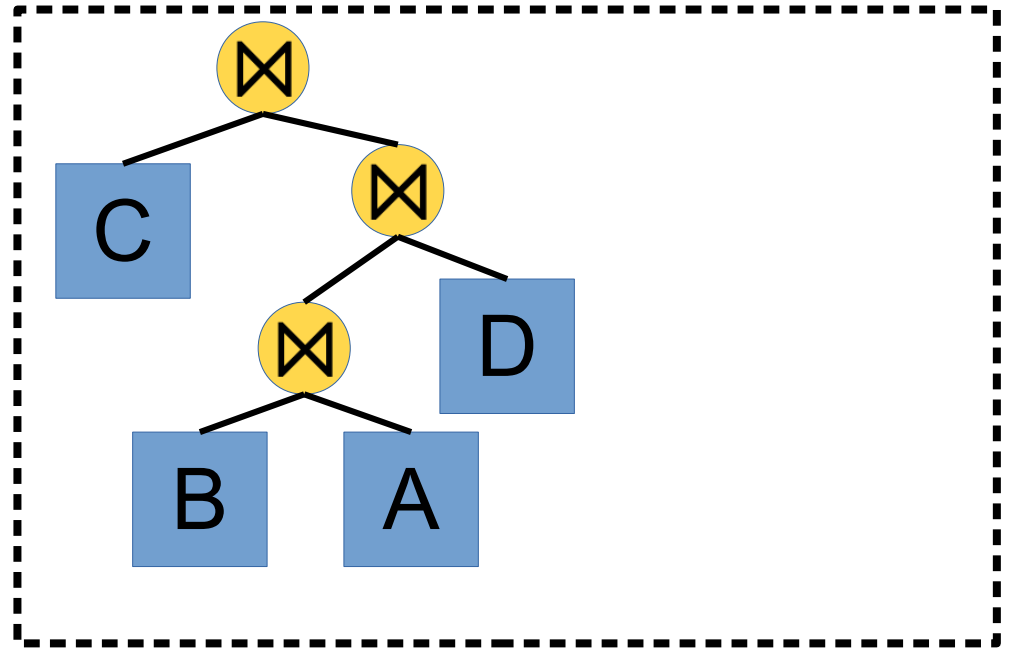
$([[BA]D], C), (C, [[BA]D])$



# ReJOIN

- Each state is a partial join order
- Each action fuses two partial orderings
- Reward is the optimizer cost

State



Possible actions:



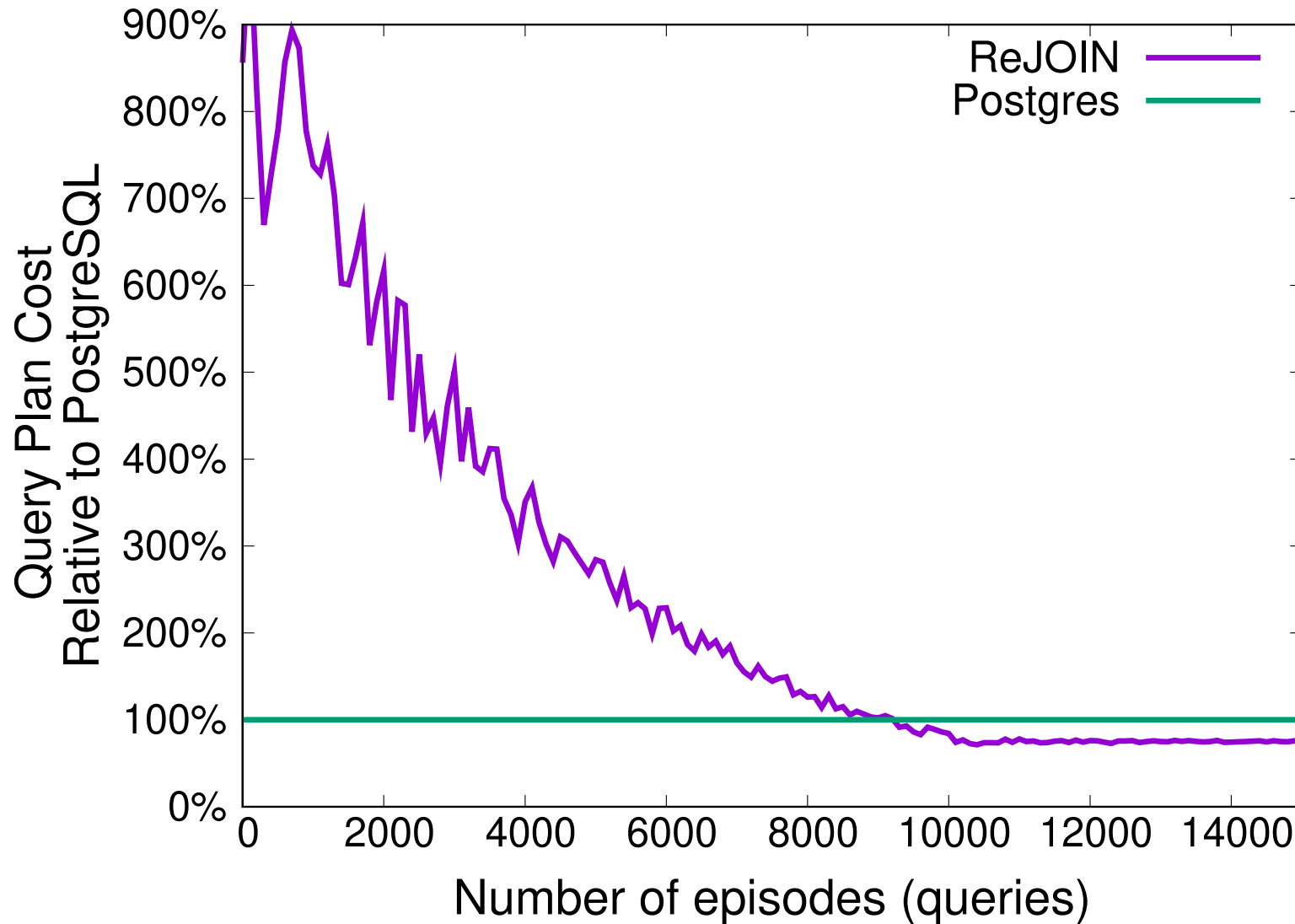
# Results

- PPO algorithm
- JOB (join order benchmark) queries
- 114 queries on real-world (IMDB) data
- 10 held-out
  
- We made you a VM: <https://git.io/imdb>
- **Harder** to train, **better** plans, **faster** queries, **stronger** component.





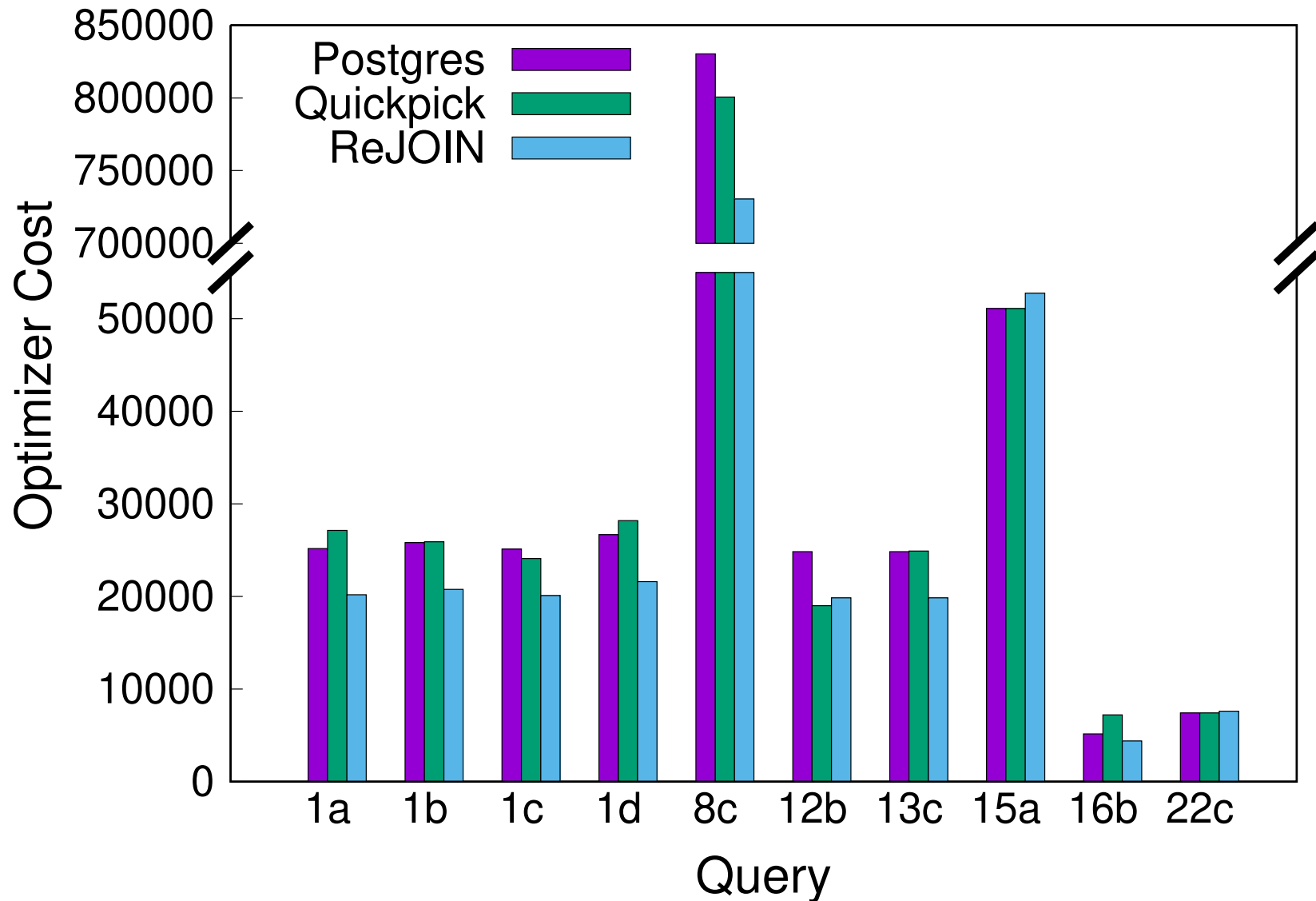
# Convergence



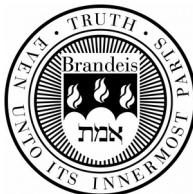
**Harder to train: convergence is long and noisy.**



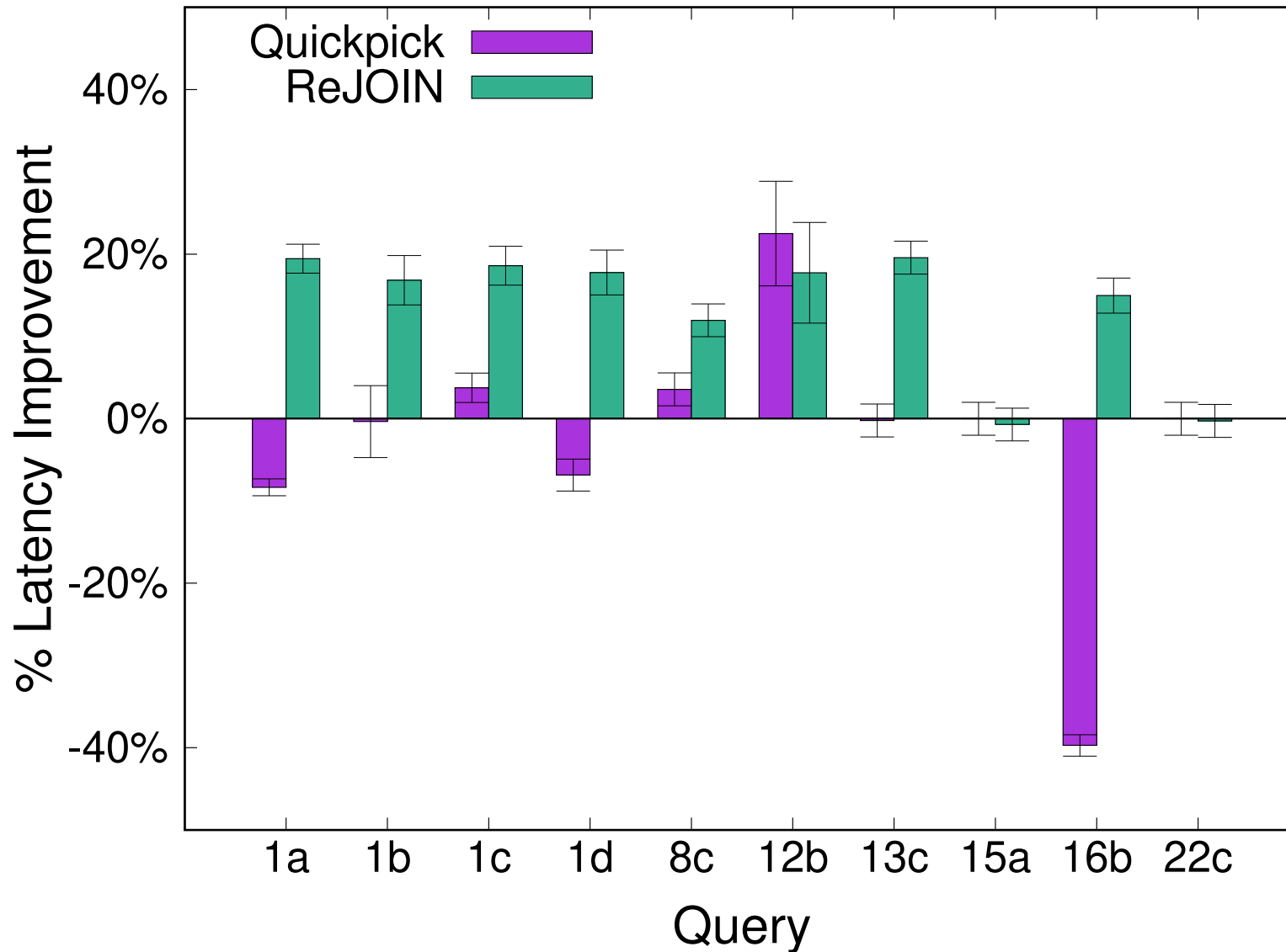
# Optimizer Cost



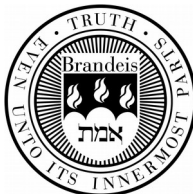
**Better results according to cost model**



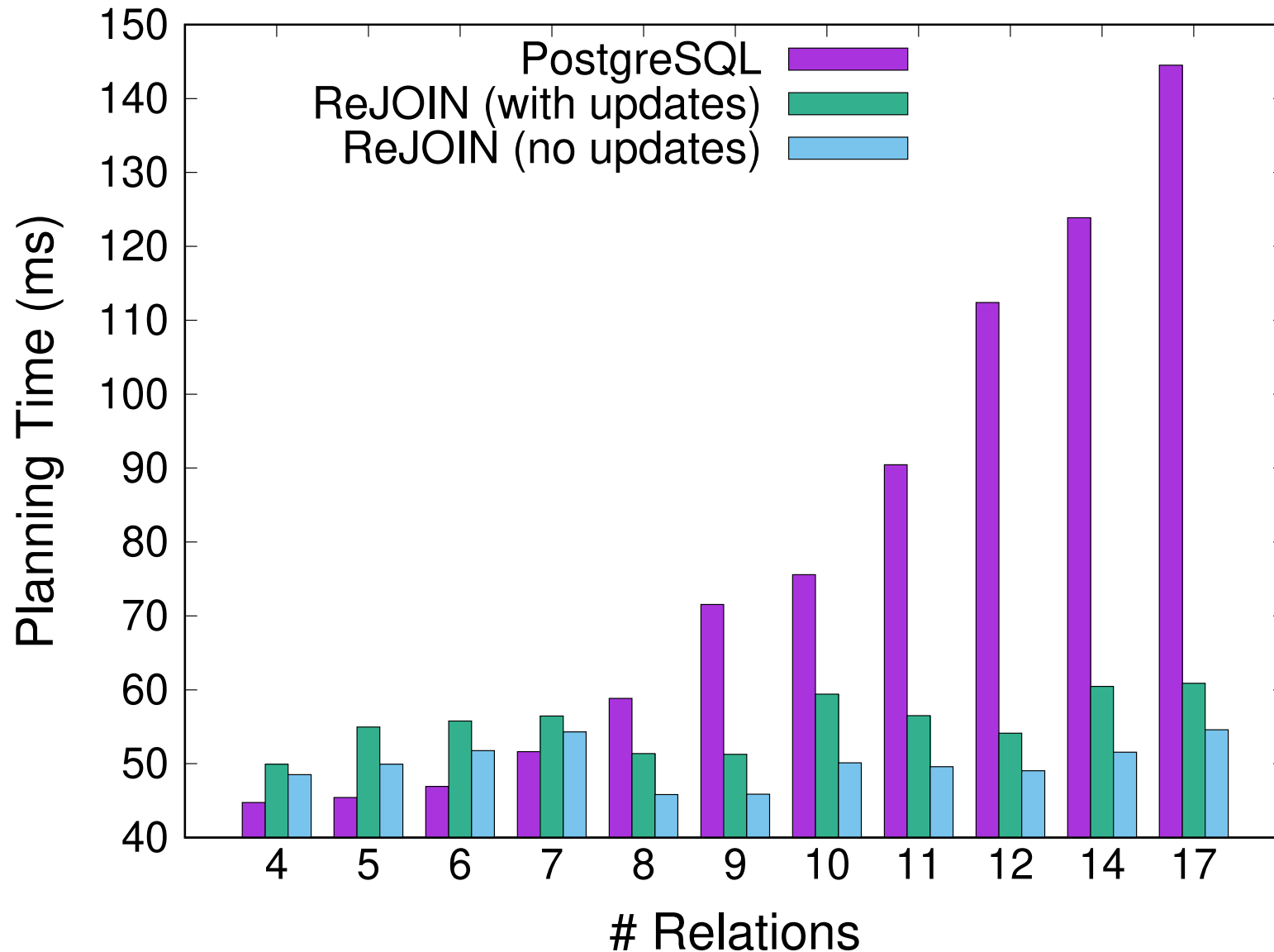
# Latency



**Faster latency when actually executed**



# Planning Time



**Stronger join order selection algorithm**



# Challenges & Next Steps

- Challenge #1: Dependence on cost model
  - Train directly based on latency? What about the bad plans?
- Challenge #2: Convergence / bootstrapping
  - Learn from demonstration? Promising, but we can't have our cake and eat it too.
- Challenge #3: Debugging
  - Activation maps? Much more difficult to explain a decision than in a traditional optimizer.



# Challenges & Next Steps

- Challenge #1: Dependence on cost model
  - Train directly based on latency? What about the bad plans?
- Challenge #2: Convergence / bootstrapping
  - Learn from demonstration? Promising, but we can't have our cake and eat it too.
- Challenge #3: Debugging
  - Activation maps? Much more difficult to explain a decision than in a traditional optimizer.

Common challenges among many DL / QO papers  
Addressed in submitted CIDR vision paper (under review)



# Conclusions

- If a proof-of-concept application of deep learning produced these results, imagine what a nuanced approach might achieve!

Workshop paper (aiDM@SIGMOD18):

<http://rm.cab/rejoin>



# Thanks!

- Me: Ryan Marcus
- Email: [ryan@cs.brandeis.edu](mailto:ryan@cs.brandeis.edu)
- Twitter: [@RyanMarcus](https://twitter.com/RyanMarcus)
- Web: <http://ryanmarc.us>
- These slides: <http://rm.cab/ibm18>

